

ExaStencils



<http://www.exastencils.org/>



U N I K A S S E L
V E R S I T Ä T



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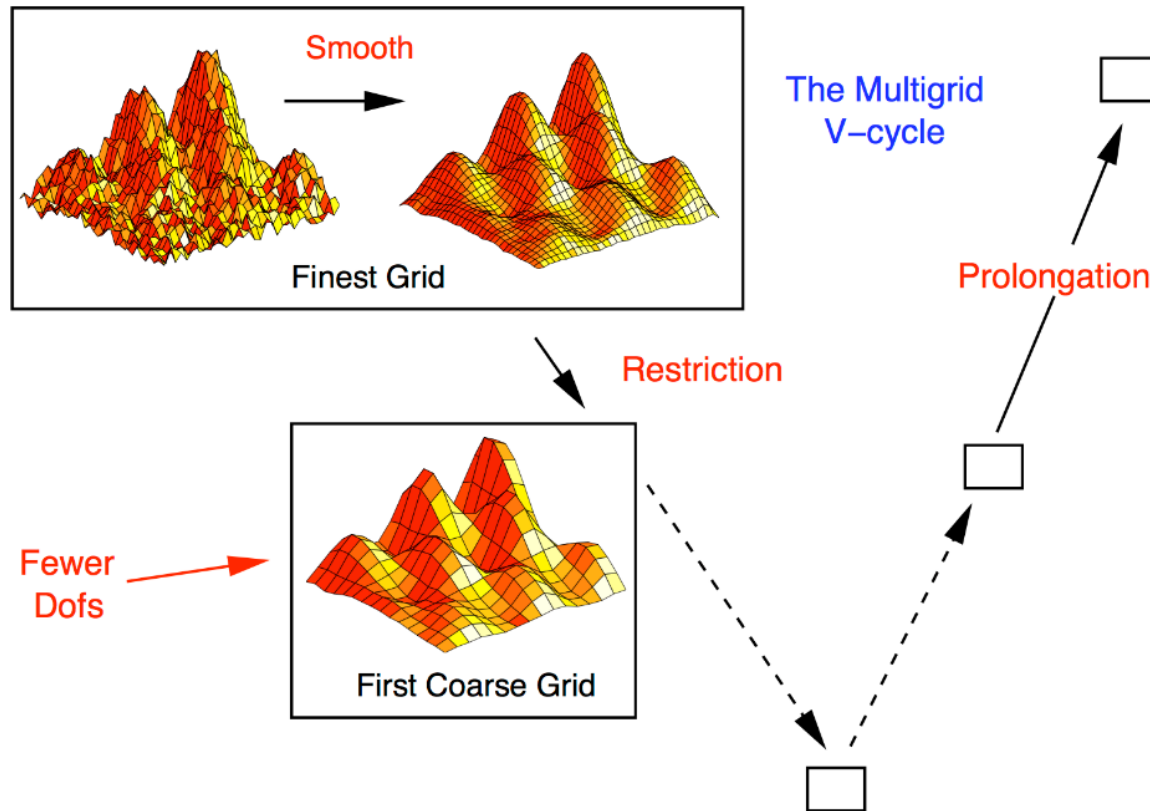
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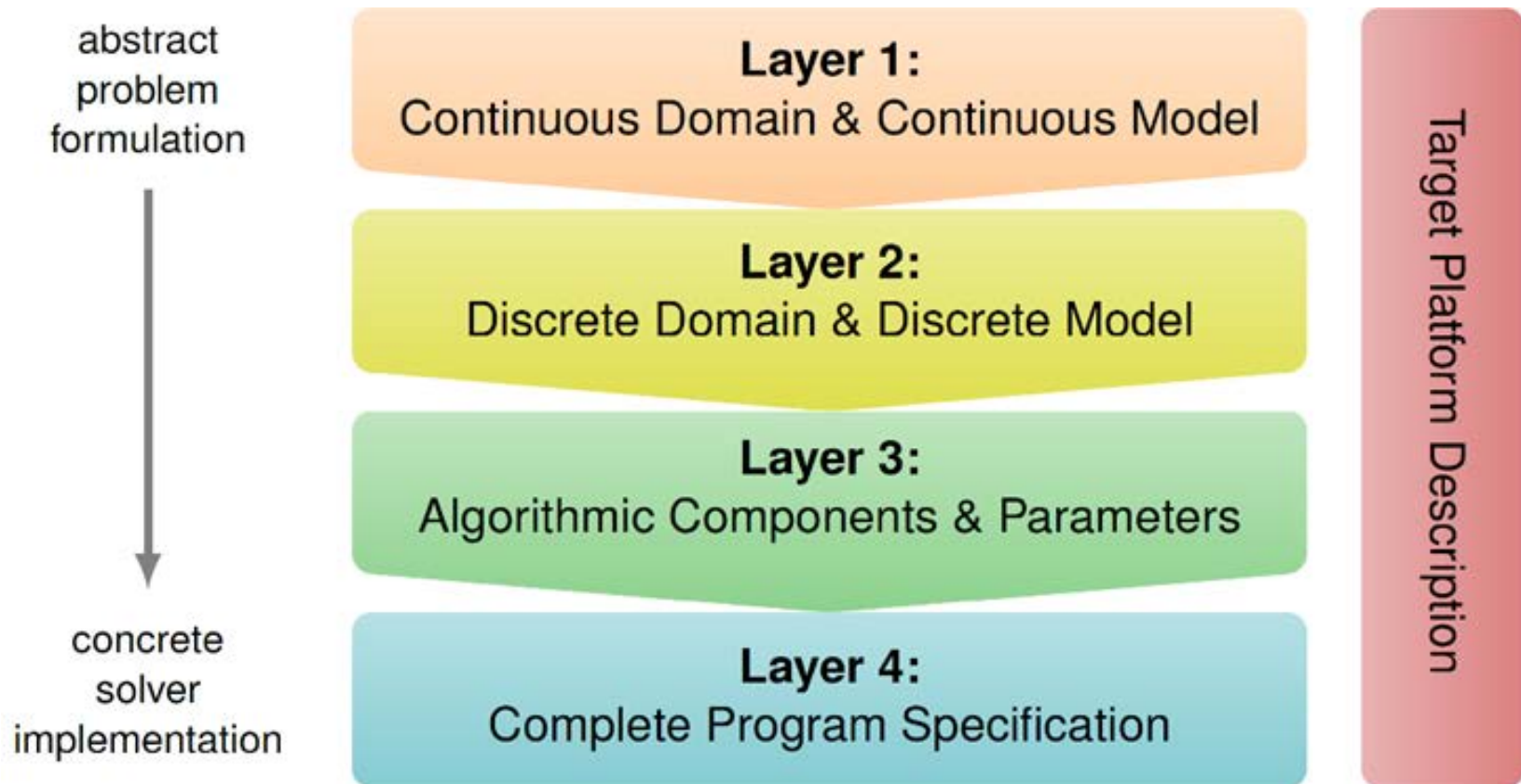
Shigeru Chiba

Stencil Domain: Multigrid



- Elliptic PDEs and systems thereof
- Discretization using finite differences or volumes
- Patch-based domains

Domain-Specific Stencil Language ExaSlang



Example: 2D Poisson with Damped Jacobi

- Layer 1 (continuous): Ops in Unicode or LaTeX symbols, partial derivative and Laplace predefined. Domains: unions of rectangles. Stencil weights calculated automatically.
- Layer 2 (discrete): Discretized functions are fields (data type, grid location), tied to a domain. Geometric information as "virtual fields", resolved to constants or field accesses.
- Layer 3 (Multigrid): Cycle and navigation through grid, access to grid levels with relative referencing. Grid transfer ops composed from default ops. Also more advanced types than Jacobi possible.
- Layer 4 (implementation): I/O and communication composition of solver parts, e.g., length of cycle.

```
/** Layer 1 **/
```

```
// domain - information is carried over from L1
```

```
Domain:  $\Omega = (0,1) \times (0,1)$  // alt.:  $\Omega = (0,1) \times (0,1)$ 
```

```
 $\partial\Omega = (x^2 - 0.5 * y^2)$  // alt.:  $\partial\Omega = 0$ 
```

```
Equation:  $-\Delta(u) = 0$  // alt.:  $-\Delta(u) = 0$ 
```

```
// optional: specify mappings for 'mnemonic' names in subsequent layers to
```

```
// override defaults
```

```
Mapping:  $\Omega \rightarrow \text{global}$ 
```

```
u  $\rightarrow$  Solution
```



ExaSlang 2

```
/** Layer 2 **/  
  
// domain - information is carried over from L1  
Domain global  
  
// fields from L1  
Field Solution@all with Real on Node of global = 0.0  
Field RHS@all with Real on Node of global = 0.0  
  
// boundary conditions from L1  
Field Solution@finest on boundary = vf_boundaryCoord_x ** 2 - 0.5 *  
vf_boundaryCoord_y ** 2  
Field Solution@(all but finest) on boundary = 0.0  
  
// (discretized) operators from L1  
Operator Laplace from Stencil {  
    [ 0, 0] => 2.0 / ( vf_gridWidth_x ** 2 ) + 2.0 / ( vf_gridWidth_y ** 2 )  
    [-1, 0] => -1.0 / ( vf_gridWidth_x ** 2 )  
    [ 1, 0] => -1.0 / ( vf_gridWidth_x ** 2 )  
    [ 0, -1] => -1.0 / ( vf_gridWidth_y ** 2 )  
    [ 0, 1] => -1.0 / ( vf_gridWidth_y ** 2 )  
}
```



ExaSlang 3

```
/** Layer 3 **/  
  
/* fields and operators from L2 are carried over automatically */  
  
// new fields  
Field Residual      from Solution  
  
// override inherited boundary conditions where applicable  
override bc for Residual@finest with 0.0  
  
// generate default inter-grid operators for node-based discretizations  
Operator RestrictionStencil from default restriction on Node with 'linear'  
Operator CorrectionStencil from default prolongation on Node with 'linear'  
  
// create smoother function  
Function Smoother@all {  
  Val omega : Real = 0.8  
  repeat 3 times {  
    Solution =  
      Solution + omega * diag_inv ( Laplace ) * ( RHS - Laplace * Solution )  
  }  
}
```



ExaSlang 3 (continued)

```
/** Layer 3 **/  
  
// create v-cycle function  
Function VCycle@(all but coarsest) {  
    Smoother ( )  
  
    Residual = RHS - ( Laplace * Solution )  
    RHS@coarser = RestrictionStencil * Residual  
  
    Solution@coarser = 0.0  
    VCycle@coarser ( )  
  
    Solution += CorrectionStencil * Solution@coarser  
  
    Smoother ( )  
}  
  
Function VCycle@coarsest {  
    /** CGS **/  
}
```



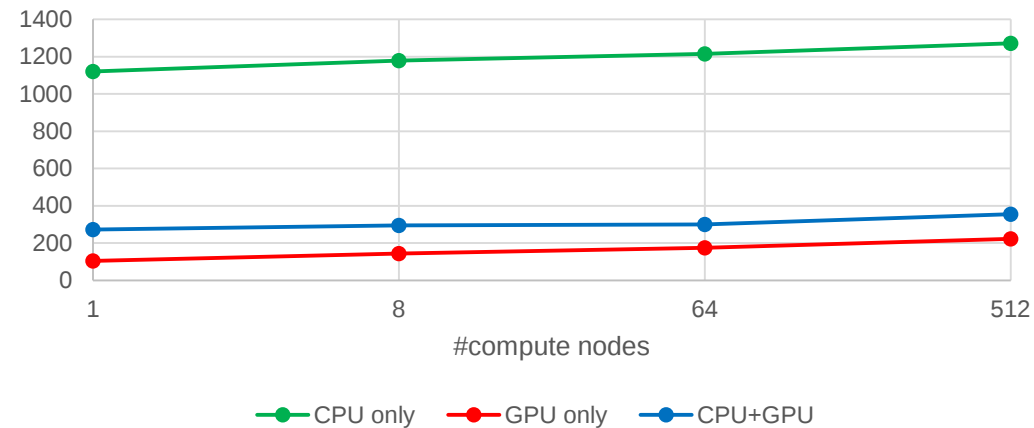
ExaSlang 4

```
/** Layer 4 **/  
  
// create main function  
Function Application ( ) : Unit {  
    /* init code */  
  
    Var resStart : Real = NormResidual@finest ( )  
    Var curRes    : Real = resStart  
  
    repeat until curRes < 1.0E-5 * resStart {  
        VCycle@finest ( )  
        curRes = NormResidual@finest ( )  
    }  
  
    /* de-init code */  
}
```

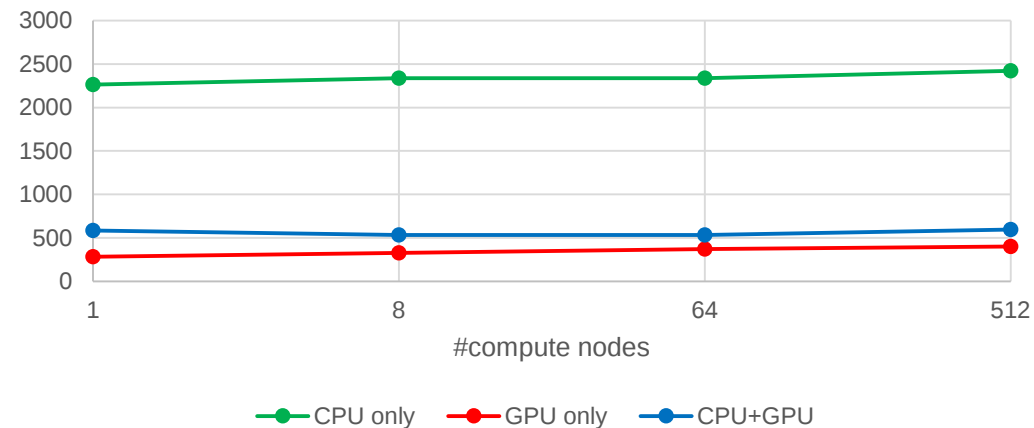
Platform Variability

- (The same) ExaSlang input can be mapped to different hardware platforms
 - "classical" CPUs
 - GPUs
 - FPGAs
 - ARM
 - and blends of these
- (Automatic) Parallelization using
 - MPI
 - OpenMP (on CPUs)
 - CUDA (on GPUs)
 - ...and combinations
- First results from PizDaint@CSCS
 - Weak scaling
 - 4 MPI threads per node
 - 512^3 unknowns per node

time per cycle [ms] for 3D constant coefficients



time per cycle [ms] for 3D variable coefficients



- Beyond Poisson's equation

- Stokes
- Navier-Stokes
- Image processing
- ...

- Each with specialized

- Grids (may be non-uniform, non-axisparallel, staggered)
- Discretizations and boundary treatment
- Solvers (e.g. block smoothers, non-linear multigrid, etc.)

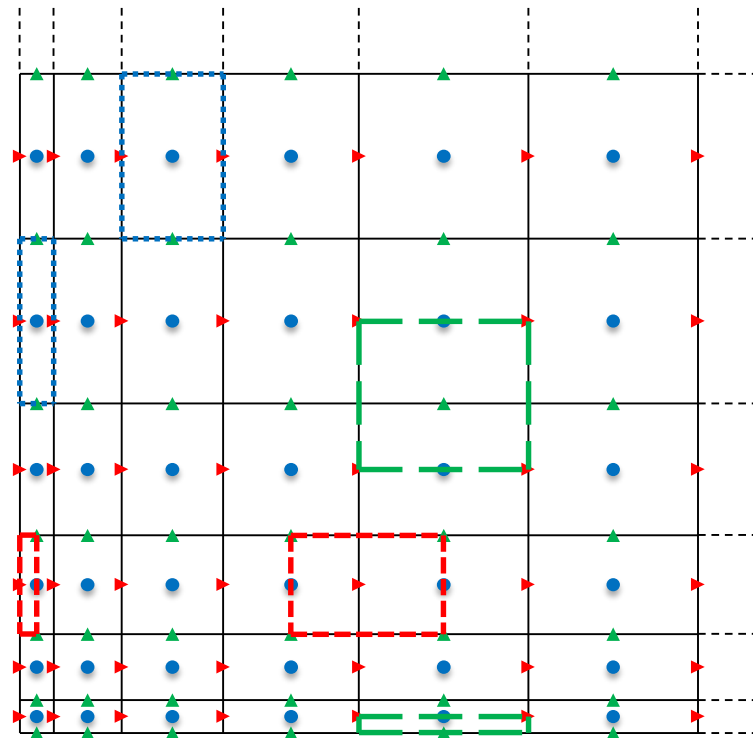
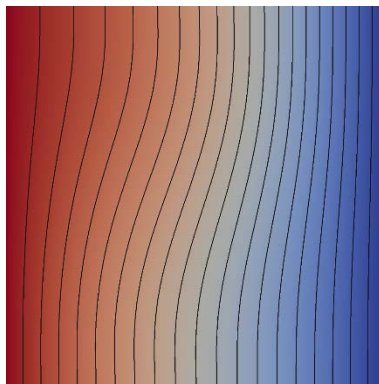
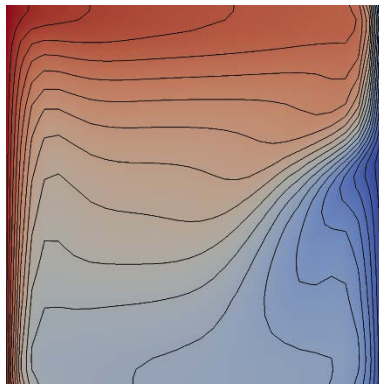
A Block Smoother for Stokes

```
loop over p {
  solve locally {
    u@[0, 0] => rhs_u@[0, 0] ==
      Laplace * u@[0, 0] + dxLeft * p@[0, 0]
    u@[1, 0] => rhs_u@[1, 0] ==
      Laplace * u@[1, 0] + dxLeft * p@[1, 0]
    ...
    p@[0, 0] => rhs_p@[0, 0] ==
      dxRight * u@[0, 0] + dyRight * v@[0, 0]
  }
}
```

ExaSlang 4

Fully Generated Real-World Application

- Collaboration with Austria (U. Graz, G. Haase) and Chile (U. Santiago de Chile, D. Vasco)
- 3D non-Newtonian and non-isothermal fluid flows
- Finite volume discretization on non-uniform staggered grids



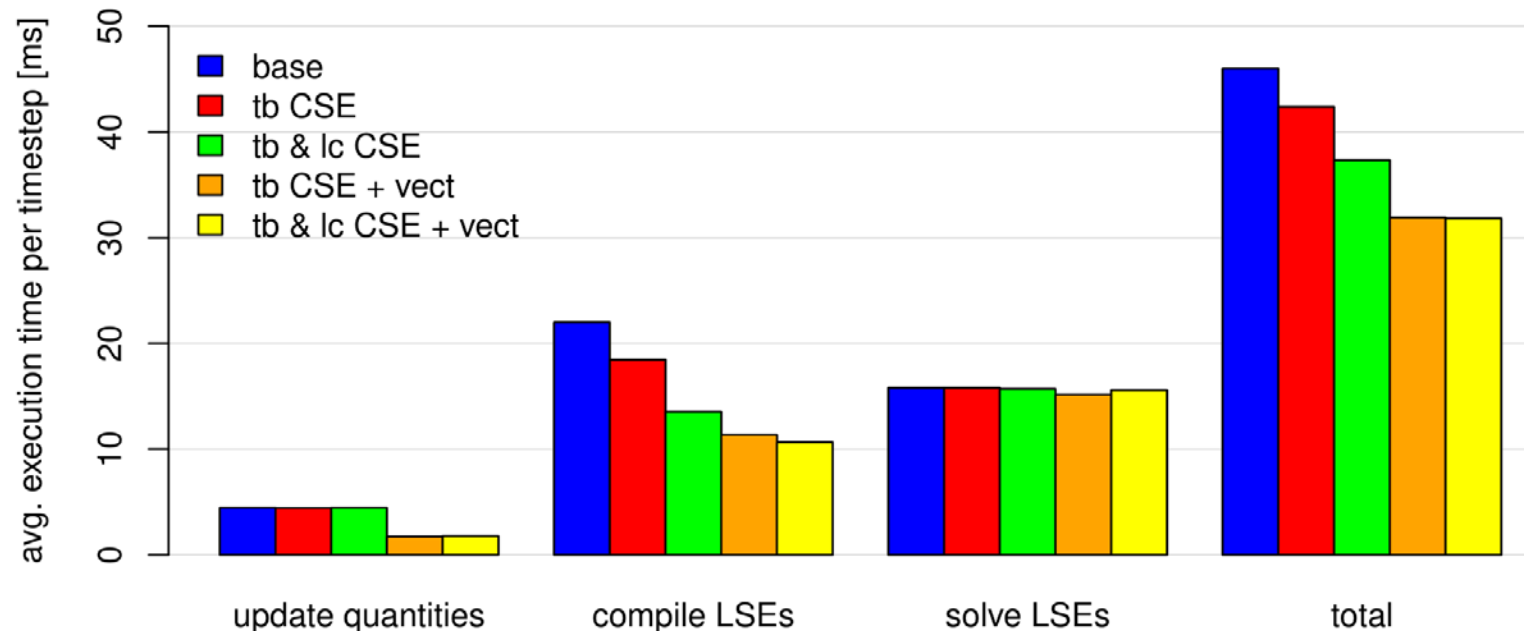
- values associated with the cell centers, e.g. p and θ
- ▶ values associated with the x-staggered grid, e.g. U
- ▲ values associated with the y-staggered grid, e.g. V
- control volumes associated with cell-centered values
- control volumes associated with x-staggered values
- control volumes associated with y-staggered values

Node-Level Optimizations: Compute-Bound

■ Compute Optimizations

- Arithmetic optimization (to maintain the numerical stability of stencil codes)
 - Common subexpression elimination (CSE)
 - text-based (tb) version: in a loop iteration
 - loop-carried (lc) version: between loop iterations
- Vectorization for Intel x86 (incl. Xeon Phi), IBM BlueGene/Q and ARM NEON

Example: non-Newtonian flow simulation

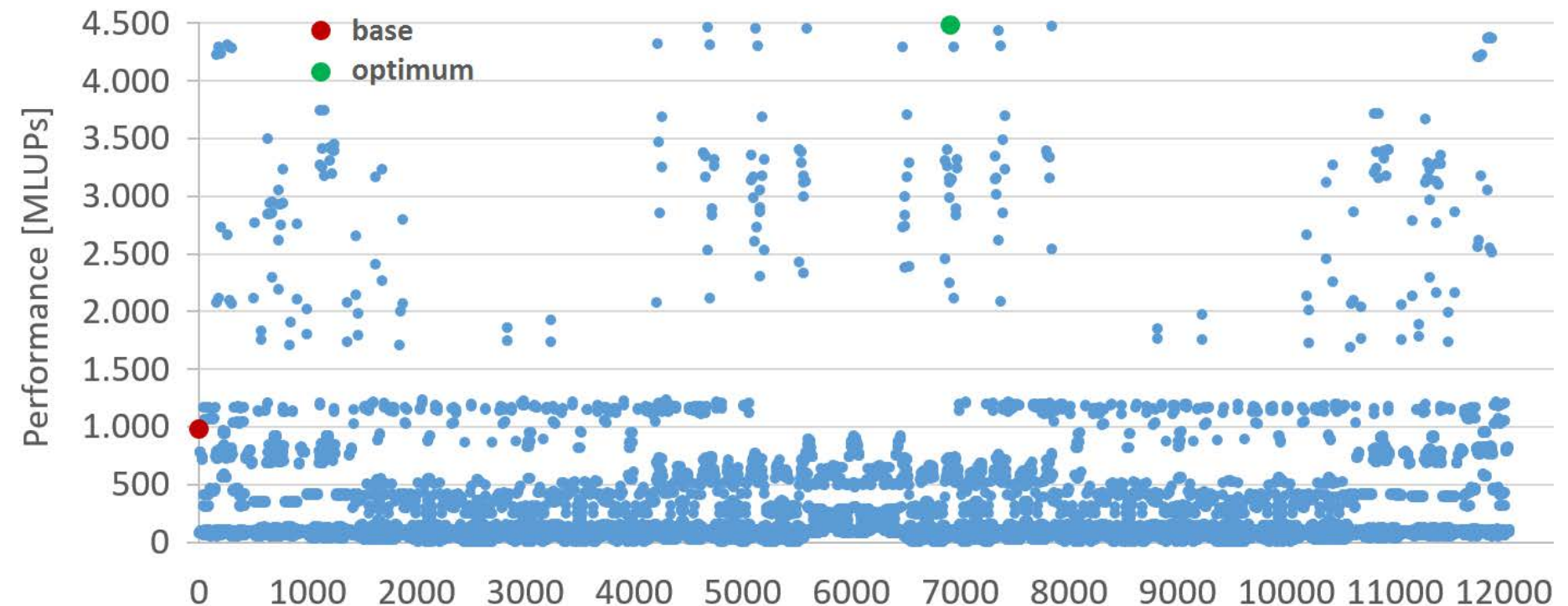




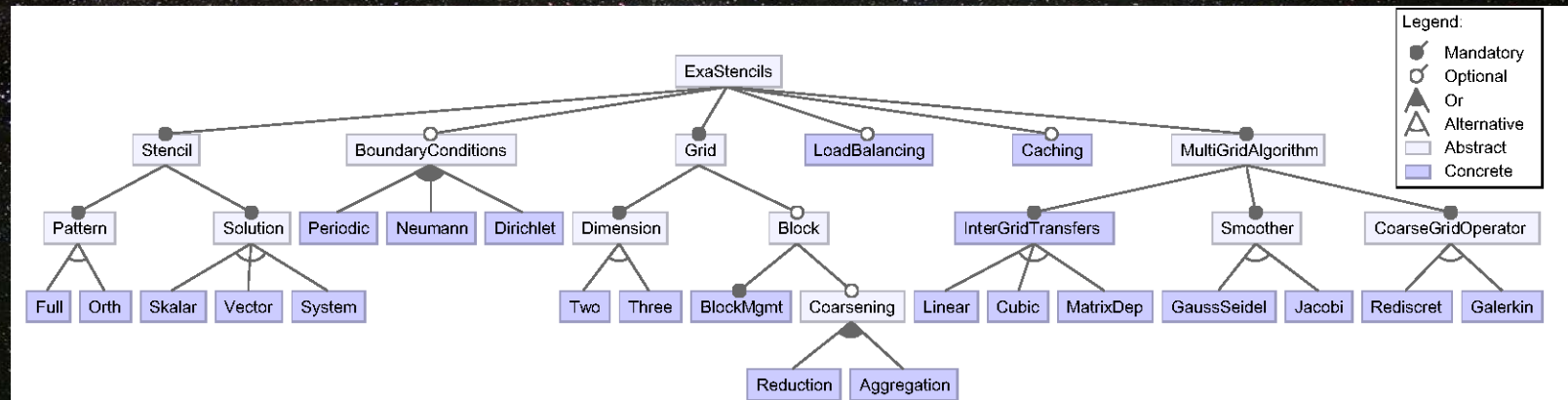
Node-Level Optimizations Memory-Bound

- Memory-Bandwidth Optimizations
 - Polyhedral transformations (temporal blocking)
 - perform search-space exploration
 - choose schedule heuristically

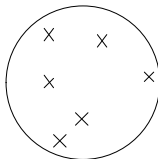
Example: exploration for 3D 7-point Jacobi



Taming the Variability of the Code-Generator



Sampling



Learning



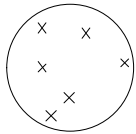
Performance-Influence Model

$$189392.754871324 * \text{root} + -5341.1497460973 * \text{cells} + -$$
$$1097.39668559875 * \text{post} + 6852.58846993721 * \text{GradientSolver} +$$
$$752.542387648181 * \text{BiCGSTABSolver} + 1.88645994097499 * \text{cells} * \text{post} +$$
$$\text{post} + 547.236997276589 * \text{GradientSolver} * \text{pre} * \text{pre} +$$
$$113.547148735501 * \text{cells} * \text{GradientSolver} + 0.706383967601375 * \text{cells} * \text{cells} * \text{cells} + 385.840181761216 * \text{GradientSolver} * \text{post} * \text{post} +$$
$$2.72707363219899 * \text{cells} * \text{pre} + -39.9822314861407 * \text{BiCGSTABSolver} * \text{pre} * \text{pre} + -11.9701281275527 * \text{cells} * \text{GradientSolver} * \text{pre} * \text{pre} +$$
$$8.2288112361045 * \text{cells} * \text{GradientSolver} * \text{post} * \text{post} +$$
$$112.152829956782 * \text{post} * \text{SeqSOR}$$

Identifying Performance-Optimal Configurations

Can we identify performance-optimal parameter settings for different mathematical problems?

Sampling



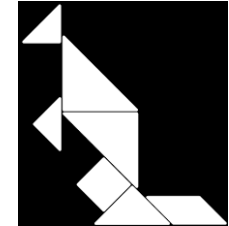
Learning



Performance-Influence Model

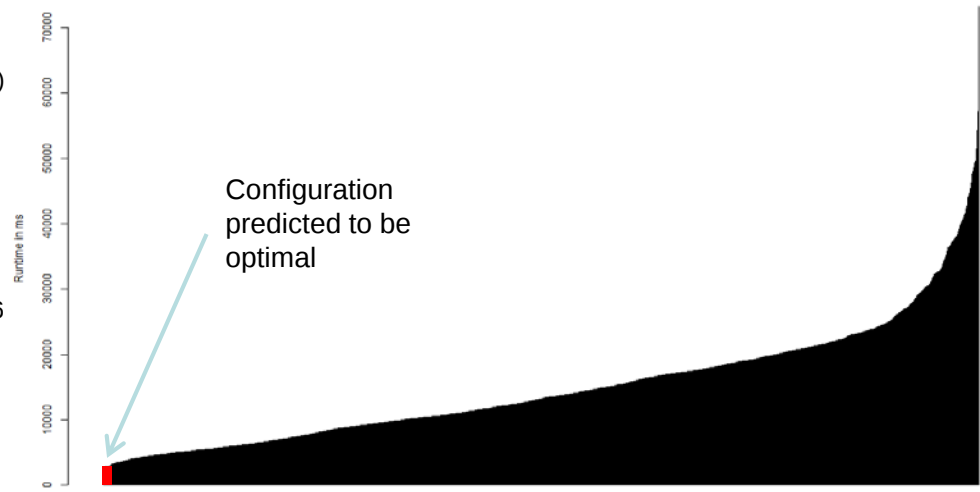
```
189392.754871324 * root + -5341.1497460973 * cells +-  
1097.39668559875 * post + 6852.58846993721 * GradientSolver +  
752.542387648181 * BiCGSTABSolver + 1.88645994097499 * cells * post *  
post + 547.236997276589 * GradientSolver * pre * pre +-  
113.547148735501 * cells * GradientSolver * post * post +  
cells * cells + 385.840181761216 * GradientSolver * post * post +  
2.72707363219899 * cells * pre + -39.9822314861407 * BiCGSTABSolver *  
pre * pre + -11.9701281275527 * cells * GradientSolver * pre * pre +-  
8.2288112361045 * cells * GradientSolver * post * post +  
112.152829956782 * post * SeqSOR
```

Mixed-Integer
Nonlinear Optimizer



Performance-influence model for 2D Poisson with const. coeff.

```
2667.4 - 343.8 * log2( numNodes ) * numPre - 926.5 * log2( numNodes ) *  
numPost - 33.3 * log2( numNodes ) - 317.5 * log2( numNodes ) - 76.9 *  
mpi_CustomDatatypes + 1545.2 * numPre - 6.4E7 * numPost - 0.1 * log2(  
numNodes ) * ( 64 - numNodes ) - 0.3 * log2( numNodes ) * ( 64 - numNodes )  
* log2( ranksPerNode ) + 2.3 * log2( numNodes ) * numPre * ( 64.0 -  
numNodes ) - 0.4 * log2( numNodes ) * numPre * ( 64.0 - numNodes ) * log2(  
tileSize_x ) - 0.5 * log2( numNodes ) * numPre * ( 64.0 - numNodes ) * log2(  
ranksPerNode ) - 0.1 * log2( numNodes ) * numPre * ( 64.0 - numNodes ) *  
log2( ranksPerNode ) * vectorize + 0.06 * numPost * ( 1.0E9 - tileSize_x ) +  
101.0 * log2( numNodes ) * numPost * log2( numNodes ) - 0.4 * log2(  
ranksPerNode ) * ( 64.0 - ranksPerNode ) + 1.0 * log2( ranksPerNode ) *  
numNodes - 111.1 * log2( ranksPerNode ) - 174.3 * log2( numNodes ) + 0.006  
* log2( ranksPerNode ) * numNodes * ( 64 - numNodes ) - 0.7 * log2(  
numNodes ) * log2( ranksPerNode ) - 0.03 * log2( numNodes ) * ( 64.0 -  
ranksPerNode ) - 0.03 * log2( numNodes ) * ( 64 - numNodes ) - 4.5 * log2(  
numNodes ) - 2.7 * mpi_CustomDatatypes * ranksPerNode - 16.3 *  
mpi_CustomDatatypes * ( 4.0 - minLevel ) - 86.7 *  
omp_parallelizeLoopOverDimensions + 2.2 * mpi_CustomDatatypes *  
ranksPerNode * log2( numNodes )
```



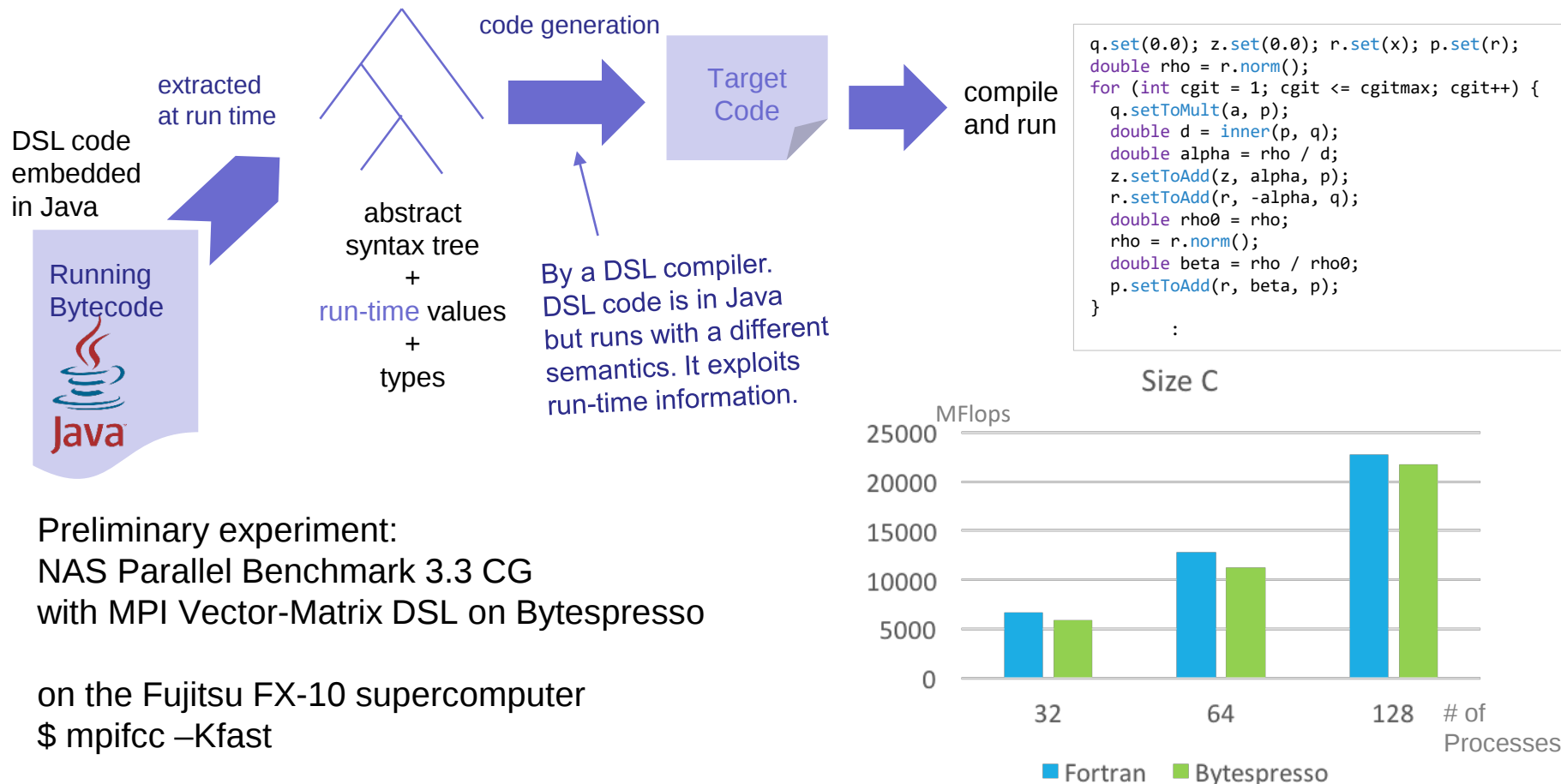
Japan: An Embedded DSL for Stencil Computing

Bytespresso:

A new approach of *deep reification* for language embedding of domain-specific code.

DSL code embedded in Java is dynamically extracted and compiled into target (native) code.

In ExaStencils: a platform for an ExaSlang-like embedded DSL.



Preliminary experiment:

NAS Parallel Benchmark 3.3 CG

with MPI Vector-Matrix DSL on Bytespresso

on the Fujitsu FX-10 supercomputer

\$ mpifcc -Kfast

Case Study: Generation of Multigrid Solvers in SPIRAL

- SPIRAL: rule-driven optimizing code generator for digital signal-processing transforms, linear algebra
- Simple multigrid solver (cooperation with Franz Franchetti, CMU):
square 2D Poisson, Richardson smoother, Dirichlet boundary
- Compared to ExaStencils, SPIRAL's domain is much narrower
- Special single-core optimization, but missing Kronecker optimization (fusion of sum of products)
- Algebraic view, comparable to ExaSlang 3 without knowledge of PDEs

$$\text{MGSolvePDE}_{n,\omega,r,m} \rightarrow [\text{I}_{n^2} \mid 0_{n^2}] \cdot \left(\prod_{i=0}^{m-1} \text{MGCycle}_{n,\omega,r} \right) \cdot \begin{bmatrix} 0_{n^2} \\ \text{I}_{n^2} \end{bmatrix}$$

$$\text{MGCycle}_{n,\omega,r} \rightarrow \text{CGC}_{n,\omega,r} \cdot \text{Richardson}_{n,\omega,r}$$

$$\text{CGC}_{n,\omega,r} \rightarrow \begin{bmatrix} \text{CoarseError}_{n,\omega,r} \\ 0_{n^2} \mid \text{I}_{n^2} \end{bmatrix}$$

$$\text{CoarseError}_{n,\omega,r} \rightarrow \text{Interpolate}_n \cdot \text{Scatter}_n \cdot \text{Solve}_{n,\omega,r} \cdot \text{Gather}_n \cdot \text{Residual}_n$$

$$\text{Interpolate}_n \rightarrow \text{Tridiag}_n(\sqrt{2}/2, \sqrt{2}, \sqrt{2}/2) \otimes \text{Tridiag}_n(\sqrt{2}/2, \sqrt{2}, \sqrt{2}/2)$$

$$\text{Scatter}_n \rightarrow \text{S}_{1,2}^{n \times (n-1)/2} \otimes \text{S}_{1,2}^{n \times (n-1)/2}$$

$$\text{Solve}_{n,\omega,r} \rightarrow \begin{cases} \frac{1}{4} \text{I}_1, & n = 1 \\ \left[\text{I}_{((n-1)/2)^2} \mid 0_{((n-1)/2)^2} \right] \cdot \text{MGCycle}_{(n-1)/2,\omega,r} \cdot \begin{bmatrix} 0_{((n-1)/2)^2} \\ \text{I}_{((n-1)/2)^2} \end{bmatrix}, & n > 1 \end{cases}$$

$$\text{Gather}_n \rightarrow \text{G}_{1,2}^{(n-1)/2 \times n} \otimes \text{G}_{1,2}^{(n-1)/2 \times n}$$

$$\text{Residual}_n \rightarrow [\text{Tridiag}_n(1, -2, 1) \otimes \text{I}_n + \text{I}_n \otimes \text{Tridiag}_n(1, -2, 1) \mid \text{I}_{n^2}]$$

$$\text{Richardson}_{n,\omega,r} \rightarrow \prod_{i=0}^{r-1} \begin{bmatrix} \text{ResidueLaplace}_{n,\omega} & \omega \text{I}_{n^2} \\ 0_{n^2} & \text{I}_{n^2} \end{bmatrix}$$

$$\text{ResidueLaplace}_{n,\omega} \rightarrow \text{Tridiag}_n(\omega, 0.5 - 2\omega, \omega) \otimes \text{I}_n + \text{I}_n \otimes \text{Tridiag}_n(\omega, 0.5 - 2\omega, \omega)$$



- **Cooperation**
 - SPIRAL (CMU / Imperial College / Terra-Neo)
 - RSDFT (Computational Materials Chemistry, Ruhr-Universität Bochum)
 - Non-Newtonian flows (University of Graz / Mechanical Engineering, University of Santiago, Chile)
 - Performance-influence models for Multigrid (Applied Mathematics, University of Zaragoza)
 - Stencil variability for porous media (EXA-DUNE)
- **Special Section in Concurrency and Computation: Practice and Experience**
 - Six papers from Dagstuhl Seminar 15161 on Advanced Stencil-Code Engineering (April 2015)
 - Of these, five papers are new collaborations, four of them with participation of ExaStencils

Thanks for your attention!